The Subgraph Isomorphism Problem: Three New Ideas


## The Subgraph Isomorphism Problem

■ Given a little pattern graph and a large target graph, find "a copy of" the pattern inside the target.

- We'll look at the non-induced or monomorphism variation: find an injective mapping that preserves adjacency, but not necessarily non-adjacency.

(4)


## Existing Algorithms

■ VF2: widely used, and extremely fast on small, sparse, low degree graphs. But if it doesn't find a result within ten milliseconds, it is unlikely to find a result within a day.
■ LAD and SND: very clever CP-like algorithms with deep reasoning. But for some larger target graphs, a single propagation takes over a second.

■ We'll do much less reasoning, but can manage $>100,000$ propagations per second.

## A CP-Like Model

- One variable per vertex in the pattern graph. The domain is the vertex in the target graph that it gets mapped to.
■ For each adjacent pair of vertices in the pattern graph, their values must be adjacent in the target graph.
- All variables have different values.

■ We can filter initial domains using degree, neighbourhood degree sequence, loops, ...

# Supplemental Graphs 

## Distance-Based Filtering

- If two vertices are distance $d$ apart in the pattern graph, they can only be mapped to a pair of vertices which are within distance $d$ (or less) in the target graph.



## Distance-Based Filtering

- $G^{d}$ is the graph with the same vertex set as $G$, and an edge between $v$ and $w$ if the distance between $v$ and $w$ in $G$ is at most $d$.
■ For any $d$, a subgraph isomorphism $i: P \hookrightarrow T$ is also a subgraph isomorphism $i^{d}: P^{d} \hookrightarrow T^{d}$.



## Implied Constraints

- We're now trying to find a mapping $i$ which is simultaneously a subgraph isomorphism

|  | $i$ | $: P$ | $\hookrightarrow$ |
| :--- | :--- | :--- | :--- |
| and | $i^{2}$ | $: P^{2}$ | $\hookrightarrow$ |
| $T^{2}$ |  |  |  |
| and | $i^{3}$ | $: P^{3} \hookrightarrow$ | $T^{3}$ | and so on.

- So we can filter on adjacency, degree, neighbourhood degree sequences, etc, in these graph pairs too.
- Open question: we can take the intersection, but is there a stronger operation which we can compute with reasonable complexity?


## Path-Based Filtering

■ In practice, this only seems to be useful for $d \leq 3$.

- Stronger: if two vertices in the pattern graph are connected by $k$ paths of length exactly $d$, then they can only be mapped to a pair of vertices which have at least $k$ paths of length exactly $d$ between them.
- We can also look at cycles: a vertex in a cycle of length $k$ must be mapped to a vertex in a cycle of length $k$.
- We can do this as using graph transformation too. Let $G^{[d, k]}$ be the (loopy) graph with the same vertex set as $G$, and an edge between $v$ and $w$ if there are at least $k$ paths or cycles of length exactly $d$ between $v$ and $w$ in $G$.
- This is NP-hard to produce in general, but for $d \leq 3$ and small $k$ we can calculate it quickly in practice.


## Supplemental Graphs

■ We just build these graphs once, at the top of search.

- We could recreate them whenever a vertex disappears from every target domain, but this is costly.
- We can cache these if we have a database of target graphs.
- Other transformations are sometimes helpful. We can either pick a good, general set, or use domain knowledge.
- Different transformations are helpful for other variations of the problem.
- For the induced variant, we can also look at $\bar{G}$.
- And we can compose transformations.


## Is This Actually New?

■ SND uses distances (not paths) for filtering.

- Inference using $G^{d}$ is stolen from $k$-clique algorithms.


## Counting All-Different

## Injectivity / Enforcing All-Different

- When assigning $D_{v} \leftarrow w$, remove $w$ from every other domain. If a domain ends up being empty, fail and backtrack.
- This enforces the constraint, but does not provide much additional inference.


## Hall Sets

- If we have a subset of $n$ variables, whose domains include exactly $n$ values between them, then those values can only be used by those variables.
- If we have a subset of $n$ variables, whose domains include less than $n$ values between them, then we cannot give every variable a different value.


## Régin's Matching-Based All-Different Filtering

■ Build a bipartite graph, with variables on the left, values on the right, and edges for allowed assignments.
■ Find a matching that covers every variable, or fail and backtrack if there isn't one.
■ Remove every edge (variable-value assignment pair) which cannot occur in any maximum cardinality matching.

## All-Different Filtering via Counting

- Go through each variable, from smallest domain to largest, and take the union of the domains as we go along.
- If we reach a failed Hall set, fail.
- If we reach a Hall set, remove all these values from every remaining domain, reset the counters, and keep going.
- This is much faster, especially when domains are already bitsets, but may miss some deletions that matching would find.


## All-Different Filtering via Counting



## All-Different Filtering via Counting



## All-Different Filtering via Counting



## All-Different Filtering via Counting



## All-Different Filtering via Counting



## All-Different Filtering via Counting



## All-Different Filtering via Counting



## All-Different Filtering via Counting



## All-Different Filtering via Counting



## All-Different Filtering via Counting



## All-Different Filtering via Counting

- In this case we found both variable-value assignments which could never occur.
■ Had we done tie-breaking in a different order, we could have missed one of these.


## Is This Actually New?

■ Claude-Guy Quimper and Toby Walsh used counting as preprocessing in the context of set variables, but they use it to determine whether it's worth trying a matching.
■ Javier Larrosa and Gabriel Valiente counted neighbours for SIP.

- There are other propagators for bounds consistency.
- I can't find this variation in the literature, possibly because it doesn't enforce any particular kind of consistency.


## Backjumping

## Backtracking is Dumb

■ When we hit a failure, we could backtrack.

- Maybe the previous assignment didn't contribute to the failure, though.


## Conflict-Directed Backjumping

- Conflict-directed backjumping keeps a conflict set for each variable. We track which assignments removed a value from a variable. When we backtrack, if we did not cause the failure, we can keep going backwards.
- But copying conflict sets gives a performance hit inside a "fast and dumb" algorithm.


## Variable-Directed Backjumping

■ When we assign and fail, return which variables were involved in the failing constraint.

- When we cannot find any value to assign to a variable, return the union of the variables in failed sub-searches, plus ourself. (Intuition: we might be able to succeed, if either we had another value, or if another problematic variable had another value.)
- When a search subproblem fails, determine whether the assignment we just made removed any values from any of the failing variables. If not, jump back another step straight away.
- We don't need to track any additional information to do this, because we have both the domains we were given, and the clone which has had propagation applied to it.


## Backjumping plus All-Different

- All-different(D) implies all-different(D') for any subset D' of D.

■ If we can produce a small failed Hall set, we might be able to jump back further.
■ We can just return the variables that we've seen so far.

- This sometimes helps a lot in practice.
- Maybe we could do more work to find an even better (not necessarily smaller) set?


## Is This Actually New?

- Current subgraph isomorphism algorithms just backtrack.

■ Neil Moore implemented lazy explanation generation for CP, but in a different way.
■ Guillaume Rochart, Narendra Jussien and Franois Laburthe worked out better explanations for all-different via flows, in the context of interactive CP.

## Preliminary Results

## Is This Any Good?

■ Fast and dumb isn't really fashionable for CP.

- Backjumping isn't fashionable anywhere...

■ We'll look at the 2063 benchmark instances used to evaluate LAD and SND.

- A mix of random, randomly structured, heavily structured, and real-world graphs.


## Cumulative Performance



## Per-Instance Comparison




## Is Each Feature Helpful?



## Is Backjumping Any Good?



## How Much Worse is Counting All-Different?



## Very Quick Attempt at Threaded Tree-Search

- Half an hour's coding to check that the idea is sane.

■ Distance 1 splitting to a queue, no extra load balancing yet.
■ No parallelisation of supplemental graph construction yet.
■ Speculative parallelism, so linear speedup should not be expected.

■ Not even for unsat instances, due to backjumping!
■ 16 threads.

## Very Quick Attempt at Threaded Tree-Search



## Very Quick Attempt at Threaded Tree-Search



## Proper Thread Parallelism?

■ Work order matters: parallel diversity is a good alternative to discrepancy search.

- Proper load balancing is necessary.

■ Lack of parallel supplemental graph construction means we can't ignore Amdahl's law.

- Backjumping makes all this quite fiddly.
- It's easy to implement using Cilk, but we lose control of the work stealing strategy.
- We could theoretically get an absolute slowdown due to backjumping. This is preventable by not "sharing backwards", but might not be worth it.


## What's Next?

■ All the variants (labels, directed edges, induced, ...)
■ Other supplemental graphs

- I can concoct additional transformations which can close half of the remaining open instances, but they're rather specialised.
■ Portfolios and instance-specific algorithm configuration?
■ Does this legitimise special transformations?
- Symmetries and dominance?
- Better typesetting for $\bar{P} \nLeftarrow \bar{T}$ ?
http://dcs.gla.ac.uk/~ciaran
c.mccreesh.1@research.gla.ac.uk

